## Gauss Curvature and the Gauss-Bonnet Theorem

Let  $\vec{\Phi}: D \to \mathbb{R}^3$ , be a smooth parametrized surface  $S(\vec{\Phi}(D) = S, \ \vec{T}_u \times \vec{T}_v \neq 0)$ . We want to develop a definition of the Gauss Curvature of a surface at a point  $p \in S$ .

Let's start with 2 curves in the x, y plane:  $y = x^2$  and  $y = 4x^2$ .



Our intuition tells us that the curvature of  $y = 4x^2$  at the point (0,0) is larger than the curvature of  $y = x^2$  at (0,0). We can also intuitively conclude that the notion of curvature should be related to the second derivative of the function at that point. Not surprisingly, y'' = 8 for the curve  $y = 4x^2$  at (0,0), and y'' = 2for the curve  $y = x^2$  at (0,0). (In this particular example, the curvature of the 2 curves actually does equal 8 and 2, however, in general, the calculation of curvature is a more complicated than just calculating the  $2^{nd}$  derivative.) Now let's parametrize both curves:

$\overrightarrow{c_1}(t) = \langle t, t^2 \rangle$	$\overrightarrow{c_2}(t) = < t, 4t^2 >$
$\vec{c}_1'(t) = <1,2t>$	$\vec{c}_{2}'(t) = <1,8t>$
$\vec{c}_1''(t) = < 0,2 >$	$\vec{c}_{2}''(t) = <0.8>$

Notice the upward pointing unit normal vector at the point (0,0) to both curves is

$$\vec{n} = < 0, 1 >.$$

Finally, notice that the "curvatures" we calculated above can be gotten by:

$$\vec{c}_1''(t) \cdot \vec{n} = <0,2> < 0,1> = 2$$
  
 $\vec{c}_2''(t) \cdot \vec{n} = <0,8> < 0,1> = 8.$ 

Thus it should not surprise us to see  $2^{nd}$  derivatives dotted with a unit normal vector in a formula for curvature of a surface.

To define curvature for a surface we start by defining:

$$E = \left| \frac{\partial \vec{\Phi}}{\partial u} \right|^2, \quad F = \frac{\partial \vec{\Phi}}{\partial u} \cdot \frac{\partial \vec{\Phi}}{\partial v}, \qquad G = \left| \frac{\partial \vec{\Phi}}{\partial v} \right|^2$$

It can be shown through a messy calculation that:

$$\left|\vec{T}_u \times \vec{T}_v\right|^2 = EG - F^2.$$

Let  $W = EG - F^2$ .

We know that a unit normal vector,  $\overrightarrow{n}$ , on the surface S is given by:

$$\vec{n} = \frac{\vec{T}_u \times \vec{T}_v}{\left|\vec{T}_u \times \vec{T}_v\right|} = \frac{\vec{T}_u \times \vec{T}_v}{\sqrt{W}}.$$

Now we define 3 functions l, m, n at a point  $p \in S$  by:

$$l(p) = \vec{n}(u, v) \cdot \frac{\partial^2 \vec{\phi}}{\partial u^2}$$
$$m(p) = \vec{n}(u, v) \cdot \frac{\partial^2 \vec{\phi}}{\partial u \partial v}$$
$$n(p) = \vec{n}(u, v) \cdot \frac{\partial^2 \vec{\phi}}{\partial v^2}$$

We now define the **Gauss Curvature**, k(p), for  $p \in S$ :

$$\boldsymbol{k}(\boldsymbol{p})=\frac{ln-m^2}{W}.$$

Ex. Planes have curvature 0 at every point.

The general form of a plane in  $\mathbb{R}^3$  has the form:

$$\vec{\Phi}(u,v) = \langle (a_1u + a_2v + a_3), (b_1u + b_2v + b_3), (c_1u + c_2v + c_3) \rangle;$$
  
where  $a_i, b_i, c_i$  are constants.

Notice that since  $\vec{\Phi}(u, v)$  is linear in u and v we have:

$$\frac{\partial^2 \vec{\phi}}{\partial u^2} = 0, \quad \frac{\partial^2 \vec{\phi}}{\partial u \partial v} = 0, \quad \frac{\partial^2 \vec{\phi}}{\partial v^2} = 0 \implies$$
$$l(p) = \vec{n}(u, v) \cdot \frac{\partial^2 \vec{\phi}}{\partial u^2} = 0$$
$$m(p) = \vec{n}(u, v) \cdot \frac{\partial^2 \vec{\phi}}{\partial u \partial v} = 0$$
$$n(p) = \vec{n}(u, v) \cdot \frac{\partial^2 \vec{\phi}}{\partial v^2} = 0.$$

Thus we have:

$$k(p)=\frac{ln-m^2}{W}=0.$$

Ex. Calculate the Gauss curvature of the sphere  $x^2 + y^2 + z^2 = R^2$ .

 $\vec{\Phi}(\phi,\theta) = \langle R \cos\theta \sin\phi, R \sin\theta \sin\phi, R \cos\phi \rangle; \ 0 \le \phi \le \pi, \text{ and } 0 \le \theta \le 2\pi.$  $\vec{T}_{\phi} = \langle R \cos\theta \cos\phi, R \sin\theta \cos\phi, -R \sin\phi \rangle$  $\vec{T}_{\theta} = \langle -R \sin\theta \sin\phi, R \cos\theta \sin\phi, 0 \rangle$ 

$$\begin{split} \vec{T}_{\phi} \times \vec{T}_{\theta} &= \begin{vmatrix} \vec{\iota} & \vec{j} & \vec{k} \\ Rcos\theta cos\phi & Rsin\theta cos\phi & -Rsin\phi \\ -Rsin\theta sin\phi & Rcos\theta sin\phi & 0 \end{vmatrix} \\ \vec{T}_{\phi} \times \vec{T}_{\theta} &= R^2 sin^2 \phi cos\theta \vec{\iota} + R^2 sin^2 \phi sin\theta \vec{j} + R^2 sin\phi cos\phi \vec{k}. \\ |\vec{T}_{\phi} \times \vec{T}_{\theta}| &= \sqrt{R^4 sin^4 \phi cos^2 \theta + R^4 sin^4 \phi sin^2 \theta + R^4 sin^2 \phi cos^2 \phi} \\ &= R^2 sin\phi. \\ \text{Unit normal} = \vec{n} &= \frac{\vec{T}_{\phi} \times \vec{T}_{\theta}}{|\vec{T}_{\phi} \times \vec{T}_{\theta}|}; \\ &= \frac{R^2 sin^2 \phi cos\theta \vec{\iota} + R^2 sin^2 \phi sin\theta \vec{j} + R^2 sin\phi cos\phi \vec{k}}{R^2 sin\phi} \\ \vec{n} &= sin\phi cos\theta \vec{\iota} + sin\phi sin\theta \vec{j} + cos\phi \vec{k} . \end{split}$$

$$\frac{\partial^{2}\vec{\phi}}{\partial\phi^{2}} = < -R\cos\theta\sin\phi, -R\sin\theta\sin\phi, -R\cos\phi >$$
$$\frac{\partial^{2}\vec{\phi}}{\partial\phi\partial\theta} = < -R\sin\theta\cos\phi, R\cos\theta\cos\phi, 0 >$$
$$\frac{\partial^{2}\vec{\phi}}{\partial\theta^{2}} = < -R\cos\theta\sin\phi, -R\sin\theta\sin\phi, 0 >$$

$$l(p) = \vec{n} \cdot \frac{\partial^2 \vec{\phi}}{\partial \phi^2}$$
  
=  $< \sin\phi \cos\theta, \sin\phi \sin\theta, \cos\phi > \cdot < -R\cos\theta \sin\phi, -R\sin\theta \sin\phi, -R\cos\phi >$   
=  $-R\cos^2\theta \sin^2\phi - R\sin^2\theta \sin^2\phi - R\cos^2\phi$   
=  $-R[\sin^2\phi(\cos^2\theta + \sin^2\theta) + \cos^2\phi] = -R$ 

$$\begin{split} m(p) &= \vec{n} \cdot \frac{\partial^2 \vec{\phi}}{\partial \phi \partial \theta} \\ &= < \sin \phi \cos \theta, \sin \phi \sin \theta, \cos \phi > \cdot < -R \sin \theta \cos \phi, R \cos \theta \cos \phi, \ 0 > \\ &= 0 \end{split}$$

$$\begin{split} n(p) &= \vec{n} \cdot \frac{\partial^2 \vec{\phi}}{\partial \theta^2} \\ &= < \sin\phi \cos\theta, \sin\phi \sin\theta, \cos\phi > \cdot < -R\cos\theta \sin\phi, -R\sin\theta \sin\phi, 0 > \\ &= -R\sin^2\phi \cos^2\theta - R\sin^2\phi \sin^2\theta \\ &= -R\sin^2\phi (\cos^2\theta + \sin^2\theta) = -R\sin^2\phi. \end{split}$$

Since  $|\vec{T}_{\phi} \times \vec{T}_{\theta}| = R^2 sin\phi$ ,  $W = |\vec{T}_{\phi} \times \vec{T}_{\theta}|^2 = R^4 sin^2\phi$ .

Finally, we have the Gauss Curvature, k(p):

$$k(p) = \frac{ln - m^2}{W} = \frac{(-R)(-R\sin^2\phi) - (0)^2}{R^4\sin^2\phi} = \frac{1}{R^2}$$

Thus the Gauss Curvature of a sphere of radius *R* is constant at all points and equal to  $\frac{1}{p^2}$ .

Notice that for a sphere of any radius R:

$$\frac{1}{2\pi} \iint_{S} k(p) dS = \frac{1}{2\pi} \iint_{S} \frac{1}{R^{2}} dS = \frac{1}{2\pi R^{2}} \iint_{S} dS = \frac{4\pi R^{2}}{2\pi R^{2}} = 2$$

 $\iint_{S} k(p) dS$  is sometimes referred to as the total curvature of the surface S.

Gauss-Bonnet Theorem:  $\frac{1}{2\pi} \iint_{S} k(p) dS = 2 - 2g$ , where *S* is a closed smooth surface in  $\mathbb{R}^3$  and g is the genus (number of holes) of the surface.

Thus,  $\frac{1}{2\pi} \iint_{S} k(p) dS$  for any ellipsoid is equal to  $\frac{1}{2\pi} \iint_{S} k(p) dS$  for any sphere (= 2), since both surfaces are genus 0 (no holes). In fact, this remarkable theorem says that if we had a sphere made of clay and distorted it into any smooth surface we like without punching a hole in it,  $\frac{1}{2\pi}$  times the integral of the Gauss curvature of that new surface over that surface (ie  $\frac{1}{2\pi}$  times the total curvature) would still be 2.