

Riemannian Metrics

Def. Let M be a smooth manifold. A **Riemannian metric** on M is a symmetric bilinear form at each point $p \in M$ that takes elements of $(X, Y) \in T_p M \times T_p M$ into a real number $g(X, Y)$ and $g(X, X) > 0$ if $X \neq 0$ (i.e. it's positive definite).

Def. A smooth manifold, M , together with a Riemannian metric, g , is called a **Riemannian manifold**, (M, g) .

Ex. If $M = \mathbb{R}^2$ and $g = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$, then $g(X, Y)$ is the standard Euclidean inner product on \mathbb{R}^2 .

$$X = (\alpha_1, \alpha_2); \quad Y = (\beta_1, \beta_2)$$

$$\langle X, Y \rangle = g(X, Y) = (\alpha_1 \quad \alpha_2) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \beta_1 \\ \beta_2 \end{pmatrix} = \alpha_1 \beta_1 + \alpha_2 \beta_2 .$$

However, if we let \bar{g} be represented by $\bar{g} = \begin{pmatrix} 2 & 1 \\ 1 & 3 \end{pmatrix}$ we would get a different inner product on \mathbb{R}^2 :

$$\begin{aligned} \langle X, Y \rangle &= \bar{g}(X, Y) = (\alpha_1 \quad \alpha_2) \begin{pmatrix} 2 & 1 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} \beta_1 \\ \beta_2 \end{pmatrix} \\ &= 2\alpha_1\beta_1 + \alpha_1\beta_2 + \alpha_2\beta_1 + 3\alpha_2\beta_2. \end{aligned}$$

Def. Let (M, g) be a Riemannian manifold. Suppose that X and Y are vectors in $T_p M$.

1. The **length of X** , denoted $\|X\|$, is defined as $\|X\| = \sqrt{g(X, X)}$

2. The **angle θ between X and Y** is defined by $\cos \theta = \frac{g(X, Y)}{\|X\| \|Y\|}$

3. X and Y are called **orthogonal** if $g(X, Y) = 0$.

Two Riemannian manifolds are considered the same if they have the same metric.

Def. Let M and N be two Riemannian manifolds. A diffeomorphism $f: M \rightarrow N$ is called an **isometry** if for all $p \in M$ the following holds:

$$\langle X, Y \rangle_p = \langle df_p(X), df_p(Y) \rangle_{f(p)} \text{ for } X, Y \in T_p M.$$

Two Riemannian manifolds are called **isometric** if there exists an isometry between them.

Given a parametrization of a manifold $\vec{\Phi}$, there is a Riemannian metric associated with $\vec{\Phi}$. We call this the **metric induced by $\vec{\Phi}$** .

Ex. Let $\vec{\Phi}(u, v) = (u, v, u^2 + v^2)$ be a parametrization of a surface S . Find the metric induced by $\vec{\Phi}$.

At $(u, v) = (1, 2)$, Let $X \in T_{(1,2,5)}S$ be given by $\langle 2, -3 \rangle$, i.e., $X = 2\vec{\Phi}_u(1, 2) - 3\vec{\Phi}_v(1, 2)$. Find $\|X\|$?

$$\vec{\Phi}_u = \langle 1, 0, 2u \rangle, \quad \vec{\Phi}_v = \langle 0, 1, 2v \rangle$$

As we saw earlier, we can get the metric induced by $\vec{\Phi}$ on S by:

$$\begin{aligned} g_{11} &= \vec{\Phi}_u \cdot \vec{\Phi}_u = 1 + 4u^2 \\ g_{12} &= g_{21} = \vec{\Phi}_u \cdot \vec{\Phi}_v = 4uv \\ g_{22} &= \vec{\Phi}_v \cdot \vec{\Phi}_v = 1 + 4v^2 \end{aligned}$$

So the metric induced by $\vec{\Phi}$ is given by:

$$g = \begin{pmatrix} 1 + 4u^2 & 4uv \\ 4uv & 1 + 4v^2 \end{pmatrix}$$

with respect to the basis $\{\vec{\Phi}_u, \vec{\Phi}_v\} = \{\langle 1, 0, 2u \rangle, \langle 0, 1, 2v \rangle\}$.

$$\|X\| = \sqrt{g(X, X)}$$

$$\text{At } (u, v) = (1, 2), \quad g = \begin{pmatrix} 5 & 8 \\ 8 & 17 \end{pmatrix}.$$

$X = \langle 2, -3 \rangle$, so we can write:

$$g(X, X) = \begin{pmatrix} 2 & -3 \end{pmatrix} \begin{pmatrix} 5 & 8 \\ 8 & 17 \end{pmatrix} \begin{pmatrix} 2 \\ -3 \end{pmatrix} = \begin{pmatrix} 2 & -3 \end{pmatrix} \begin{pmatrix} -14 \\ -35 \end{pmatrix} = 77.$$

$$\text{So } \|X\| = \sqrt{77}.$$

Notice that X is also a vector in $T_{(1,2,5)}\mathbb{R}^3$. What is $\|X\|$ with respect to the Euclidean metric in \mathbb{R}^3 ?

$$\vec{\Phi}_u(1, 2) = \langle 1, 0, 2 \rangle \text{ and } \vec{\Phi}_v(1, 2) = \langle 0, 1, 4 \rangle.$$

$$\begin{aligned} X &= 2\vec{\Phi}_u(1, 2) - 3\vec{\Phi}_v(1, 2) = 2\langle 1, 0, 2 \rangle - 3\langle 0, 1, 4 \rangle \\ &= \langle 2, -3, -8 \rangle. \end{aligned}$$

In \mathbb{R}^3 the Euclidean metric is:

$$\bar{g} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\bar{g}(X, X) = \begin{pmatrix} 2 & -3 & -8 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ -3 \\ -8 \end{pmatrix}$$

$$= \langle 2, -3, -8 \rangle \cdot \langle 2, -3, -8 \rangle = 4 + 9 + 64 = 77$$

So $\|X\|_{\bar{g}} = \sqrt{77}$ (the same as before!).

The length of a vector using the induced metric will always be the same as the length from the Euclidean metric.

Let $X = \alpha \vec{\Phi}_u + \beta \vec{\Phi}_v$, and (g_{ij}) the induced metric.

Then we have:

$$\begin{aligned} g(X, X) &= (\alpha \quad \beta) \begin{pmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} \\ &= \alpha^2 g_{11} + 2\alpha\beta g_{12} + \beta^2 g_{22}. \end{aligned}$$

Now let's use the Euclidean inner product to find $\|X\|^2$:

$$\begin{aligned} X \cdot X &= (\alpha \vec{\Phi}_u + \beta \vec{\Phi}_v) \cdot (\alpha \vec{\Phi}_u + \beta \vec{\Phi}_v) \\ &= \alpha^2 \vec{\Phi}_u \cdot \vec{\Phi}_u + 2\alpha\beta \vec{\Phi}_u \cdot \vec{\Phi}_v + \beta^2 \vec{\Phi}_v \cdot \vec{\Phi}_v \\ &= \alpha^2 g_{11} + 2\alpha\beta g_{12} + \beta^2 g_{22} \\ &= g(X, X). \end{aligned}$$

In fact, the above analysis leads us to why the calculation of the induced metric gives us a matrix that is positive definite.

Suppose $\vec{\Phi}: U \subseteq \mathbb{R}^n \rightarrow M \subseteq \mathbb{R}^k$ is a parametrization of an n -dimensional manifold M , with local coordinates (x^1, \dots, x^n) . The induced metric from $\vec{\Phi}$ is:

$$g = (g_{ij}), \quad \text{where } g_{ij} = \vec{\Phi}_{x^i} \cdot \vec{\Phi}_{x^j}.$$

We can represent any vector $X \in T_p M$ by:

$$X = a_1 \vec{\Phi}_{x^1} + \dots + a_n \vec{\Phi}_{x^n}.$$

Thus we can say if $X \neq \vec{0}$:

$$\begin{aligned} 0 < X \cdot X &= (a_1 \vec{\Phi}_{x^1} + \dots + a_n \vec{\Phi}_{x^n}) \cdot (a_1 \vec{\Phi}_{x^1} + \dots + a_n \vec{\Phi}_{x^n}) \\ &= \sum_{i,j=1}^n (\vec{\Phi}_{x^i} \cdot \vec{\Phi}_{x^j}) (a_i a_j) \\ &= \sum_{i,j=1}^n g_{ij} (a_i a_j) \\ &= g(X, X). \end{aligned}$$

Ex. Let $S_+^2 \subseteq \mathbb{R}^3$ be the upper hemisphere and $S_-^2 \subseteq \mathbb{R}^3$ be the lower hemisphere parametrized by:

$$\vec{\Phi}(u, v) = (u, v, \sqrt{1 - u^2 - v^2}), \quad u^2 + v^2 < 1$$

$$\vec{\Psi}(\bar{u}, \bar{v}) = (\bar{u}, \bar{v}, -\sqrt{1 - \bar{u}^2 - \bar{v}^2}), \quad \bar{u}^2 + \bar{v}^2 < 1$$

Let $f: S_+^2 \rightarrow S_-^2$ by:

$$f(u, v, \sqrt{1 - u^2 - v^2}) = (-v, u, -\sqrt{1 - u^2 - v^2})$$

Show that f is an isometry.

Showing that f is a diffeomorphism is fairly straight-forward. Let's show that:

$$\langle X, Y \rangle_p = \langle df_p(X), df_p(Y) \rangle_{f(p)}$$

Let's start by calculating the metric on S_+^2 induced by $\vec{\Phi}$:

$$\vec{\Phi}_u = \left(1, 0, -\frac{u}{\sqrt{1-u^2-v^2}}\right) \text{ and } \vec{\Phi}_v = \left(0, 1, -\frac{v}{\sqrt{1-u^2-v^2}}\right)$$

$$g_{11} = \vec{\Phi}_u \cdot \vec{\Phi}_u = 1 + \frac{u^2}{1-u^2-v^2} = \frac{1-v^2}{1-u^2-v^2}$$

$$g_{12} = g_{21} = \vec{\Phi}_u \cdot \vec{\Phi}_v = \frac{uv}{1-u^2-v^2}$$

$$g_{22} = \vec{\Phi}_v \cdot \vec{\Phi}_v = 1 + \frac{v^2}{1-u^2-v^2} = \frac{1-u^2}{1-u^2-v^2}.$$

So given the vectors $X, Y \in T_p S_+^2$

$$X = \alpha_1 \vec{\Phi}_u + \alpha_2 \vec{\Phi}_v = \langle \alpha_1, \alpha_2 \rangle$$

$$Y = \beta_1 \vec{\Phi}_u + \beta_2 \vec{\Phi}_v = \langle \beta_1, \beta_2 \rangle$$

$$\langle X, Y \rangle_p = g(X, Y) = (\alpha_1 \quad \alpha_2) \begin{pmatrix} \frac{1-v^2}{1-u^2-v^2} & \frac{uv}{1-u^2-v^2} \\ \frac{uv}{1-u^2-v^2} & \frac{1-u^2}{1-u^2-v^2} \end{pmatrix} \begin{pmatrix} \beta_1 \\ \beta_2 \end{pmatrix}$$

$$\langle X, Y \rangle_p = \frac{\alpha_1 \beta_1 (1-v^2) + (\alpha_1 \beta_2 + \alpha_2 \beta_1) uv + \alpha_2 \beta_2 (1-u^2)}{1-u^2-v^2}.$$

Notice that:

$$\vec{\Psi}^{-1} \circ f \circ \vec{\Phi}(u, v) = \vec{\Psi}^{-1}(-v, u, -\sqrt{1-u^2-v^2}) = (-v, u) = (\bar{u}, \bar{v}).$$

So $\bar{u} = -v$ and $\bar{v} = u$.

Thus:

$$df_p = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

$$df_p(X) = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \alpha_2 \end{pmatrix} = (-\alpha_2, \alpha_1) = -\alpha_2 \Psi_{\bar{u}} + \alpha_1 \Psi_{\bar{v}}$$

$$df_p(Y) = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \beta_1 \\ \beta_2 \end{pmatrix} = (-\beta_2, \beta_1) = -\beta_2 \Psi_{\bar{u}} + \beta_1 \Psi_{\bar{v}}.$$

Now we need the induced metric \bar{g} on S_-^2 from $\bar{\Psi}$.

$$\bar{\Psi}_{\bar{u}} = \left(1, 0, \frac{\bar{u}}{\sqrt{1-\bar{u}^2-\bar{v}^2}} \right) \text{ and } \bar{\Psi}_{\bar{v}} = \left(0, 1, \frac{\bar{v}}{\sqrt{1-\bar{u}^2-\bar{v}^2}} \right)$$

$$\bar{g}_{11} = \bar{\Psi}_{\bar{u}} \cdot \bar{\Psi}_{\bar{u}} = 1 + \frac{\bar{u}^2}{1-\bar{u}^2-\bar{v}^2} = \frac{1-\bar{v}^2}{1-\bar{u}^2-\bar{v}^2}$$

$$\bar{g}_{12} = \bar{g}_{21} = \bar{\Psi}_{\bar{u}} \cdot \bar{\Psi}_{\bar{v}} = \frac{\bar{u}\bar{v}}{1-\bar{u}^2-\bar{v}^2}$$

$$\bar{g}_{22} = \bar{\Psi}_{\bar{v}} \cdot \bar{\Psi}_{\bar{v}} = 1 + \frac{\bar{v}^2}{1-\bar{u}^2-\bar{v}^2} = \frac{1-\bar{u}^2}{1-\bar{u}^2-\bar{v}^2}.$$

So

$$(\bar{g}_{ij}) = \begin{pmatrix} \frac{1-\bar{v}^2}{1-\bar{u}^2-\bar{v}^2} & \frac{\bar{u}\bar{v}}{1-\bar{u}^2-\bar{v}^2} \\ \frac{\bar{u}\bar{v}}{1-\bar{u}^2-\bar{v}^2} & \frac{1-\bar{u}^2}{1-\bar{u}^2-\bar{v}^2} \end{pmatrix}.$$

$$\langle df_p(X), df_p(Y) \rangle_{f(p)} = \begin{pmatrix} -\alpha_2 & \alpha_1 \end{pmatrix} \begin{pmatrix} \frac{1-\bar{v}^2}{1-\bar{u}^2-\bar{v}^2} & \frac{\bar{u}\bar{v}}{1-\bar{u}^2-\bar{v}^2} \\ \frac{\bar{u}\bar{v}}{1-\bar{u}^2-\bar{v}^2} & \frac{1-\bar{u}^2}{1-\bar{u}^2-\bar{v}^2} \end{pmatrix} \begin{pmatrix} -\beta_2 \\ \beta_1 \end{pmatrix}$$

$$= \frac{\alpha_2\beta_2(1-\bar{v}^2) + (-\alpha_2\beta_1 - \alpha_1\beta_2)(\bar{u}\bar{v}) + \alpha_1\beta_1(1-\bar{u}^2)}{1-\bar{u}^2-\bar{v}^2}.$$

But $\bar{u} = -v$ and $\bar{v} = u$ so $1 - \bar{u}^2 - \bar{v}^2 = 1 - u^2 - v^2$, and:

$$\begin{aligned} & \langle df_p(X), df_p(Y) \rangle_{f(p)} \\ &= \frac{\alpha_2\beta_2(1-u^2) - (\alpha_2\beta_1 + \alpha_1\beta_2)(-v)(u) + \alpha_1\beta_1(1-v^2)}{1-u^2-v^2} \\ &= \frac{\alpha_1\beta_1(1-v^2) + (\alpha_2\beta_1 + \alpha_1\beta_2)(uv) + \alpha_2\beta_2(1-u^2)}{1-u^2-v^2} = \langle X, Y \rangle_p. \end{aligned}$$

Thus f is an isometry.

Given a Riemannian metric on M , one can define new, non-isometric, metrics on M by dividing an existing metric by a positive function. For example, we could take the Euclidean metric on a unit ball in \mathbb{R}^n and let:

$$g_{ii} = \frac{1}{(1-\|x\|^2)^2} \quad \text{and} \quad g_{ij} = 0 \quad \text{for } i \neq j.$$

Or we could take the upper half plane in \mathbb{R}^2 and let:

$$g_{ii} = \frac{1}{y^2} \quad \text{and} \quad g_{ij} = 0 \quad \text{for } i \neq j.$$

Proposition: Every smooth manifold, M , has a Riemannian metric.