Def: Let U be an open set in \mathbb{R}^m , we say:

$$\vec{f}: U \to \mathbb{R}^n \text{ by:}$$

$$\vec{f}(x_1, \dots, x_m) = (f_1(x_1, \dots, x_m), f_2(x_1, x_2, \dots, x_m), \dots, f_n(x_1, \dots, x_m))$$
is **smooth** if $f_i(x_1, \dots, x_m)$ has continuous partial derivatives of all orders for $i = 1, \dots, n$.

So if
$$\vec{\Phi}(u, v) = (x(u, v), y(u, v), z(u, v))$$
, then $\vec{\Phi}$ is smooth if:
 $\vec{\Phi}_u = (\frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u});$ $\vec{\Phi}_v = (\frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, \frac{\partial z}{\partial v})$
 $\vec{\Phi}_{uu} = (\frac{\partial^2 x}{\partial u^2}, \frac{\partial^2 y}{\partial u^2}, \frac{\partial^2 z}{\partial u^2});$ $\vec{\Phi}_{uv} = (\frac{\partial^2 x}{\partial u \partial v}, \frac{\partial^2 y}{\partial u \partial v}, \frac{\partial^2 z}{\partial u \partial v}), \dots$

has continuous partial derivatives of all orders.

Def. Let $U \subseteq \mathbb{R}^2$ be an open set. A **surface patch** (i.e. a parametrization)

 $\overrightarrow{\Phi}: U \to \mathbb{R}^3$ of a surface, S, is called regular if it is smooth and the vectors:

$$\overrightarrow{\Phi}_{u} = \left(\frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u}\right)$$
 and $\overrightarrow{\Phi}_{v} = \left(\frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, \frac{\partial z}{\partial v}\right)$

are linearly independent at all points $(u, v) \in U$. This is equivalent to saying: $\vec{\Phi}_u \times \vec{\Phi}_v \neq 0$ for any point $(u, v) \in U$.

- Def. If S is a surface, an **allowable surface patch** for S is a regular surface patch, $\overrightarrow{\Phi}: U \to \mathbb{R}^3$, such that $\overrightarrow{\Phi}$ and $\overrightarrow{\Phi}^{-1}$ are continuous (this is called a **homeomorphism**) from U to an open subset of S. A **smooth or regular surface** is a surface, S, such that for any point $p \in S$, there is an allowable patch, $\overrightarrow{\Phi}$, such that $p \in \overrightarrow{\Phi}(U)$. A collection, A, of allowable surface patches for a surface S such that every point of S is in the image of at least one patch in A is called an **atlas** for the smooth surface S.
- Def. (Alternative Definition) A subset $S \subseteq \mathbb{R}^3$ is a **smooth or regular surface** if for each point $p \in S$ there exists an open set, $U \subseteq \mathbb{R}^2$, an open neighborhood Q of p in \mathbb{R}^3 and a surjective continuous function $\overrightarrow{\Phi}: U \to Q \cap S$ (surjective means every point $q \in Q \cap S$ has a point $p \in U$ such that $\overrightarrow{\Phi}(p) = q$) such that:
 - 1) $\overrightarrow{\Phi}$ is smooth, i.e. if $\overrightarrow{\Phi}(u, v) = (x(u, v), y(u, v), z(u, v))$ the x(u, v), y(u, v) and z(u, v) have continuous partial derivatives of all orders.
 - 2) $\overrightarrow{\Phi}$ is a homeomorphism: $\overrightarrow{\Phi}$ is continuous and has an inverse function $\overrightarrow{\Phi}^{-1}: Q \cap S \to U$, which is also continuous.
 - 3) $\vec{\Phi}_u \times \vec{\Phi}_v \neq \vec{0}$ for any $(u, v) \in U$.



Ex. Show that the unit cylinder $S = \{(x, y, z) \in \mathbb{R}^3 | x^2 + y^2 = 1\}$ is a smooth surface.

$$\Phi(u,v) = (\cos u, \sin u, v); \quad 0 \le u \le 2\pi, \ v \in \mathbb{R}$$

is a parametrization of this cylinder, however the set:

$$V = \{(u, v) \in \mathbb{R}^2 \mid 0 \le u \le 2\pi, v \in \mathbb{R}\}$$

is not an open set in \mathbb{R}^2 .

So consider the open set:

$$U = \{ (u, v) \in \mathbb{R}^2 | 0 < u < 2\pi, v \in \mathbb{R} \}.$$

U is open but $\overrightarrow{\Phi}(U)$ does not cover all of the surface S

(the line (1,0,z) is missing).



However, $\overrightarrow{\Phi}$ is 1-1 from U into S, since if:

$$\overrightarrow{\Phi}(u_1, v_1) = \overrightarrow{\Phi}(u_2, v_2)$$
 then:

 $(\cos u_1, \sin u_1, v_1) = (\cos u_2, \sin u_2, v_2)$

This implies $v_1 = v_2$ and:

 $\cos u_1 = \cos u_2 \implies u_2 = u_1 \text{ or } 2\pi - u_1$ $\sin u_1 = \sin u_2 \implies u_2 = u_1 \text{ or } \pi - u_1.$

So $u_1 = u_2$ and $\overrightarrow{\Phi}$ is 1 - 1.

It's clear that $\overrightarrow{\Phi}$ is smooth. But we need to show that $\overrightarrow{\Phi}$ has a a continuous inverse, $\overrightarrow{\Phi}^{-1}$: $\overrightarrow{\Phi}(U) \to U$. For $\{(x, y, z) \in \overrightarrow{\Phi}(U)\}$ define:

$$\vec{\Phi}^{-1}(x, y, z) = (Tan^{-1}\left(\frac{y}{x}\right), z)$$
 if (x, y) is in the 1st quadrant

$$= \left(\frac{\pi}{2}, z\right)$$
 if $(x, y) = (0, 1)$

$$= (\pi + Tan^{-1}\left(\frac{y}{x}\right), z)$$
 if (x, y) is in the 2nd/3rd quadrant

$$= \left(\frac{3\pi}{2}, z\right)$$
 if $(x, y) = (0, -1)$

$$= (2\pi + Tan^{-1}\left(\frac{y}{x}\right), z)$$
 if (x, y) is in the 4th quadrant.

We need this messy inverse function because $-\frac{\pi}{2} < \tan^{-1} t < \frac{\pi}{2}$ and $\vec{\Phi}^{-1}$ maps $\vec{\Phi}(U)$ onto $U = (0, 2\pi) \times (-\infty, \infty)$.

It's not too difficult to show that $\overrightarrow{\Phi}^{-1}$ is continuous.

But we need another open set, W, so that $\overrightarrow{\Phi}: W \subseteq \mathbb{R}^2 \to S$ such that the points that we missed by $\overrightarrow{\Phi}: U \to S$ get covered by $\overrightarrow{\Phi}(W)$. Here we can just take:



 $W = \{(u, v) \in \mathbb{R}^2 \mid -\pi < u < \pi, v \in \mathbb{R}\}.$

By the same argument, $\overrightarrow{\Phi}$ is 1-1 on W

Now we have:

$$\vec{\Phi}_u = (-\sin u, \cos u, 0)$$
$$\vec{\Phi}_v = (0,0,1).$$

 $\overrightarrow{\Phi}_u$ and $\overrightarrow{\Phi}_v$ are linearly independent because one vector is not a multiple of the other. We can also see it by:

$$\vec{\Phi}_u \times \vec{\Phi}_v = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ -\sin u & \cos u & 0 \\ 0 & 0 & 1 \end{vmatrix} = (\cos u)\vec{i} + (\sin u)\vec{j} \neq \vec{0}$$

So S is a smooth surface.

Ex. Show that the unit sphere $S = \{(x, y, z) | x^2 + y^2 + z^2 = 1\}$ is a smooth surface.

One smooth, regular parametrization of the unit sphere is given by:

 $\vec{\Phi}(\phi,\theta) = (\cos\theta\sin\phi, \sin\theta\sin\phi, \cos\phi); \ 0 < \phi < \pi, 0 < \theta < 2\pi.$



In a manner similar to the previous example, it can be shown that

 $\vec{\Phi}$ is 1-1 and has a continuous inverse given by:

$$\vec{\Phi}^{-1}(x, y, z) = (\cos^{-1} z, Tan^{-1}\left(\frac{y}{x}\right)) \quad \text{if } (x, y) \text{ is in the 1st quadrant}$$

$$= (\cos^{-1} z, \frac{\pi}{2}) \quad \text{if } (x, y) = (0, 1)$$

$$= (\cos^{-1} z, \pi + Tan^{-1}\left(\frac{y}{x}\right)) \quad \text{if } (x, y) \text{ is in the 2}^{nd}/3rd \text{ quadrant}$$

$$= (\cos^{-1} z, \frac{3\pi}{2}) \quad \text{if } (x, y) = (0, -1)$$

$$= (\cos^{-1} z, 2\pi + Tan^{-1}\left(\frac{y}{x}\right)) \quad \text{if } (x, y) \text{ is in the 4th quadrant.}$$

To show $\vec{\Phi}_u \times \vec{\Phi}_v \neq \vec{0}$: $\vec{\Phi}_{\phi} = (\cos\theta\cos\phi, \sin\theta\cos\phi, -\sin\phi)$ $\vec{\Phi}_{\theta} = (-\sin\theta\sin\phi, \cos\theta\sin\phi, 0)$ $\vec{\Phi}_{\theta} \times \vec{\Phi}_{\theta} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \cos\theta\cos\phi & \sin\theta\cos\phi & -\sin\phi \\ -\sin\theta\sin\phi & \cos\theta\sin\phi & 0 \end{vmatrix}$ $= \cos\theta\sin^2\phi\vec{i} + \sin\theta\sin^2\phi\vec{j}$

+($\cos^2 \theta \sin \phi \cos \phi + \sin^2 \theta \sin \phi \cos \phi$) \vec{k}

$$\vec{\Phi}_{\phi} \times \vec{\Phi}_{\theta} = \cos\theta \sin^2\phi \,\vec{\iota} + \sin\theta \sin^2\phi \,\vec{j} + \sin\phi \cos\phi \,\vec{k}.$$

We can see that $\vec{\Phi}_{\phi} \times \vec{\Phi}_{\theta} \neq 0$ by showing its length is never 0. $\|\vec{\Phi}_{\phi} \times \vec{\Phi}_{\theta}\| = \sqrt{\cos^2 \theta \sin^4 \phi + \sin^2 \theta \sin^4 \phi + \sin^2 \phi \cos^2 \phi}$ $= \sqrt{(\cos^2 \theta + \sin^2 \theta) \sin^4 \phi + \sin^2 \phi \cos^2 \phi}$ $= \sqrt{\sin^4 \phi + \sin^2 \phi (\cos^2 \phi)}$ $= \sqrt{\sin^2 \phi (\sin^2 \phi + \cos^2 \phi)}$ $= |\sin \phi| > 0 \quad \text{since} \quad 0 < \phi < \pi.$ However, $\overrightarrow{\Phi}$ does not map the set:

$$U = \{(\phi, \theta) \in \mathbb{R}^2 \mid 0 < \phi < \pi, \ 0 < \theta < 2\pi\}$$

onto the unit sphere. The semicircle on the sphere of points of the form $(x, 0, z), x \ge 0$ is missing (black semi-cirlce in previous picture).

So now let's consider the set: $H = \{(x, y, z) \in \mathbb{R}^3 | x \le 0, z = 0\}$, and consider W = S - H (*W* is open). *W* is the sphere with the semicircle $(x, y, 0), x \le 0$ missing.



Now define: $\overrightarrow{\Psi}$: $U \to S - H = W$ by, $\overrightarrow{\Psi}(\phi, \theta) = (-\cos\theta\sin\phi, \cos\phi, -\sin\theta\sin\phi), 0 < \phi < \pi, 0 < \theta < 2\pi.$ As with the map $\overrightarrow{\Phi}$, $\overrightarrow{\Psi}$ is smooth and a homeomorphism. And we have:

$$\vec{\Psi}_{\phi} = (-\cos\theta\cos\phi, -\sin\phi, -\sin\theta\cos\phi)$$
$$\vec{\Psi}_{\theta} = (\sin\theta\sin\phi, 0, -\cos\theta\sin\phi)$$

$$\vec{\Psi}_{\phi} \times \vec{\Psi}_{\theta} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ -\cos\theta\cos\phi & -\sin\phi & -\sin\theta\cos\phi \\ \sin\theta\sin\phi & 0 & -\cos\theta\sin\phi \end{vmatrix}$$

 $= \cos\theta \sin^2\phi \,\vec{\imath} - (\cos^2\theta \cos\phi \sin\phi + \sin^2\theta \cos\phi \sin\phi)\vec{\jmath}$ $+ \sin\theta \sin^2\phi \,\vec{k}$

$$= (\cos\theta\sin^2\phi)\vec{\iota} - (\sin\phi\cos\phi)\vec{\jmath} + \sin\theta\sin^2\phi\vec{k}.$$

As before, $\|\vec{\Psi}_{\phi} \times \vec{\Psi}_{\theta}\| = |\sin \phi| > 0$ since $0 < \phi < \pi$. So $\|\vec{\Psi}_{\phi} \times \vec{\Psi}_{\theta}\| \neq \vec{0}$.

Since $\overrightarrow{\Phi}(U) \cup \overrightarrow{\Psi}(W) \supseteq S$ and $\overrightarrow{\Phi}$ and $\overrightarrow{\Psi}$ are homeomorphisms, S is a smooth surface.

This is not the only way to show that S is a smooth surface. For example, we could use 6 open patches (open sets) on the sphere. Each of the maps below map the set $U = \{(u, v) | u^2 + v^2 < 1\}$ in \mathbb{R}^2 onto a different hemisphere:

$$\begin{split} \vec{\Phi}_{1}(u,v) &= \left(u,v,\sqrt{1-u^{2}-v^{2}}\right); \quad z > 0 \\ \vec{\Phi}_{2}(u,v) &= \left(u,v,-\sqrt{1-u^{2}-v^{2}}\right); \quad z < 0 \\ \vec{\Phi}_{3}(u,v) &= \left(u,\sqrt{1-u^{2}-v^{2}},v\right); \quad y > 0 \\ \vec{\Phi}_{4}(u,v) &= \left(u,-\sqrt{1-u^{2}-v^{2}},v\right); \quad y < 0 \\ \vec{\Phi}_{5}(u,v) &= \left(\sqrt{1-u^{2}-v^{2}},u,v\right); \quad x > 0 \\ \vec{\Phi}_{6}(u,v) &= \left(-\sqrt{1-u^{2}-v^{2}},u,v\right); \quad x < 0 \end{split}$$

Each of these $\overrightarrow{\Phi}_i s$ has the property that it's a homeomorphism from the disk $u^2 + v^2 < 1$ in \mathbb{R}^2 onto a hemisphere and it is regular. We'll demonstrate this with $\overrightarrow{\Phi}_1(u, v)$.



- 1. $\vec{\Phi}_1$ is clearly smooth for $u^2 + v^2 < 1$.
- 2. $\overrightarrow{\Phi}_1$ is 1-1 since:

$$\vec{\Phi}_{1}(u_{1}, v_{1}) = \vec{\Phi}_{1}(u_{2}, v_{2})$$

$$\left(u_{1}, v_{1}, \sqrt{1 - u_{1}^{2} - v_{1}^{2}}\right) = \left(u_{2}, v_{2}, \sqrt{1 - u_{2}^{2} - v_{2}^{2}}\right)$$

$$\Rightarrow u_{1} = u_{2} \quad v_{1} = v_{2}, \text{ so } \vec{\Phi}_{1} \text{ is } 1\text{-}1.$$
3. $\vec{\Phi}_{1}^{-1}(x, y, z) = (x, y)$ is the continuous inverse of $\vec{\Phi}_{1}$.

4. $(\vec{\Phi}_1)_u \times (\vec{\Phi}_1)_v \neq 0$ since:

$$\left(\vec{\Phi}_{1}\right)_{u} = \left(1, 0, \frac{-u}{\sqrt{1-u^{2}-v^{2}}}\right) \qquad \left(\vec{\Phi}_{1}\right)_{v} = \left(0, 1, \frac{-v}{\sqrt{1-u^{2}-v^{2}}}\right)$$

$$\left(\vec{\Phi}_{1}\right)_{u} \times \left(\vec{\Phi}_{1}\right)_{v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 0 & \frac{-u}{\sqrt{1-u^{2}-v^{2}}} \\ 0 & 1 & \frac{-v}{\sqrt{1-u^{2}-v^{2}}} \end{vmatrix} = \frac{u}{\sqrt{1-u^{2}-v^{2}}} \vec{i} + \frac{v}{\sqrt{1-u^{2}-v^{2}}} \vec{j} + \vec{k}$$

$$\left\| \left(\vec{\Phi}_1 \right)_u \times \left(\vec{\Phi}_1 \right)_v \right\| = \sqrt{\frac{u^2}{1 - u^2 - v^2} + \frac{v^2}{1 - u^2 - v^2}} + 1 = \sqrt{\frac{1}{1 - u^2 - v^2}} \neq 0$$

So
$$\left(\vec{\Phi}_{1}\right)_{u} \times \left(\vec{\Phi}_{1}\right)_{v} \neq 0.$$

Since $\bigcup_{i=1}^{6} \overrightarrow{\Phi}_{i}(U) \supseteq S, S$ is a smooth surface.