

Green's Theorem, Stokes' Theorem, the Divergence Theorem and the Fundamental Theorem of Calculus

In this section we will show that The Fundamental Theorem of Calculus, Green's Theorem, Stokes' Theorem (on surfaces in \mathbb{R}^3), and the Divergence Theorem are all special cases of Stokes' Theorem on manifolds.

Def. A singular 0-cube, c , is a map of $c: \{0\} \rightarrow A \subseteq \mathbb{R}^n$. If ω is a zero form (i.e. a real valued function) we define:

$$\int_c \omega = \omega(c(\mathbf{0})).$$

The Fundamental Theorem of Calculus:

If f is a smooth function on $[a, b]$, then

$$\int_a^b f'(x)dx = f(b) - f(a).$$

In this case, $df = f'(x)dx$. If we call $[a, b] = I$, then The Fundamental Theorem of Calculus becomes:

$$\int_I df = \int_{\partial I} f = f(b) - f(a).$$

That is, The Fundamental Theorem of Calculus is Stokes' Theorem where $M = I$.

Green's Theorem:

Let D be a simple region and C be its boundary. Suppose that $P: D \rightarrow \mathbb{R}$ and $Q: D \rightarrow \mathbb{R}$ are smooth function, then:

$$\int_C Pdx + Qdy = \iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy.$$

Notice that if $\omega = P(x, y)dx + Q(x, y)dy$, then:

$$d\omega = \frac{\partial P}{\partial y} dy \wedge dx + \frac{\partial Q}{\partial x} dx \wedge dy = \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx \wedge dy$$

Since $C = \partial D$, we can write Green's Theorem as:

$$\int_{\partial D} \omega = \int_D d\omega.$$

This is Stokes' Theorem where $M = D$.

Stokes' Theorem (for parameterized surfaces in \mathbb{R}^3):

Let S be an oriented surface in \mathbb{R}^3 defined by a one-to-one parameterization $\vec{\Phi}: D \subseteq \mathbb{R}^2 \rightarrow \mathbb{R}^3$, where D is a simple region. Let $F(x, y, z)$ be a smooth vector field on S , then:

$$\iint_S (\nabla \times F) \cdot dS = \int_{\partial S} F \cdot ds.$$

To see that this is a special case of Stokes' Theorem on manifolds we must show that if $\omega = F \cdot ds$, then $d\omega = (\nabla \times F) \cdot dS$.

$$ds = dx \vec{i} + dy \vec{j} + dz \vec{k}$$

$$F(x, y, z) = F_1(x, y, z)\vec{i} + F_2(x, y, z)\vec{j} + F_3(x, y, z)\vec{k}$$

$$\omega = F \cdot ds = F_1 dx + F_2 dy + F_3 dz.$$

Taking the differential of each side of the last equation we get:

$$\begin{aligned} d\omega &= d(F_1 dx + F_2 dy + F_3 dz) \\ &= \left(\frac{\partial F_1}{\partial x} dx + \frac{\partial F_1}{\partial y} dy + \frac{\partial F_1}{\partial z} dz \right) \wedge dx \\ &\quad + \left(\frac{\partial F_2}{\partial x} dx + \frac{\partial F_2}{\partial y} dy + \frac{\partial F_2}{\partial z} dz \right) \wedge dy \\ &\quad + \left(\frac{\partial F_3}{\partial x} dx + \frac{\partial F_3}{\partial y} dy + \frac{\partial F_3}{\partial z} dz \right) \wedge dz \\ &= \frac{\partial F_1}{\partial y} dy \wedge dx + \frac{\partial F_1}{\partial z} dz \wedge dx + \frac{\partial F_2}{\partial x} dx \wedge dy \\ &\quad + \frac{\partial F_2}{\partial z} dz \wedge dy + \frac{\partial F_3}{\partial x} dx \wedge dz + \frac{\partial F_3}{\partial y} dy \wedge dz \end{aligned}$$

$$d\omega = \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy + \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) dy dz + \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) dz dx$$

We need to show $(\nabla \times F) \cdot dS = d\omega$.

$$\nabla \times F = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix} = \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \vec{i} + \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) \vec{j} + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \vec{k}$$

If the surface S is given by:

$$\vec{\Phi}(u, v) = (x(u, v), y(u, v), z(u, v)),$$

then:

$$dS = (\vec{\Phi}_u \times \vec{\Phi}_v) du dv$$

$$\begin{aligned} \vec{\Phi}_u \times \vec{\Phi}_v &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & \frac{\partial z}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & \frac{\partial z}{\partial v} \end{vmatrix} = \begin{vmatrix} \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} \end{vmatrix} \vec{i} - \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} \end{vmatrix} \vec{j} + \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} \vec{k} \\ &= \frac{\partial(y,z)}{\partial(u,v)} \vec{i} + \frac{\partial(z,x)}{\partial(u,v)} \vec{j} + \frac{\partial(x,y)}{\partial(u,v)} \vec{k} \end{aligned}$$

$$dS = (\vec{\Phi}_u \times \vec{\Phi}_v) du dv = \left(\frac{\partial(y,z)}{\partial(u,v)} \vec{i} + \frac{\partial(z,x)}{\partial(u,v)} \vec{j} + \frac{\partial(x,y)}{\partial(u,v)} \vec{k} \right) du dv.$$

Thus we can write:

$$\begin{aligned} (\nabla \times F) \cdot dS &= \left[\left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \vec{i} + \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) \vec{j} + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \vec{k} \right] \\ &\quad \cdot \left[\left(\frac{\partial(y,z)}{\partial(u,v)} \vec{i} + \frac{\partial(z,x)}{\partial(u,v)} \vec{j} + \frac{\partial(x,y)}{\partial(u,v)} \vec{k} \right) \right] du dv \\ &= \left[\left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \frac{\partial(y,z)}{\partial(u,v)} + \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) \frac{\partial(z,x)}{\partial(u,v)} + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \frac{\partial(x,y)}{\partial(u,v)} \right] du dv \end{aligned}$$

Notice that if $x = x(u, v)$, $y = y(u, v)$, then:

$$dx = \frac{\partial x}{\partial u} du + \frac{\partial x}{\partial v} dv; \quad dy = \frac{\partial y}{\partial u} du + \frac{\partial y}{\partial v} dv$$

$$\begin{aligned} dx \wedge dy &= \left(\frac{\partial x}{\partial u} du + \frac{\partial x}{\partial v} dv \right) \wedge \left(\frac{\partial y}{\partial u} du + \frac{\partial y}{\partial v} dv \right) \\ &= \left(\frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u} \right) du \wedge dv \\ &= \left(\frac{\partial(x,y)}{\partial(u,v)} \right) du \wedge dv. \end{aligned}$$

Similarly,

$$dy \wedge dz = \frac{\partial(y,z)}{\partial(u,v)} du \wedge dv \text{ and } dz \wedge dx = \frac{\partial(z,x)}{\partial(u,v)} du \wedge dv$$

Thus we have:

$$(\nabla \times F) \cdot dS =$$

$$\begin{aligned} &\left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) dy \wedge dz + \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) dz \wedge dx + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx \wedge dy \\ &= d\omega. \end{aligned}$$

Now we can write the following two equations:

$$\iint_S (\nabla \times F) \cdot dS = \iint_S d\omega$$

$$\int_{\partial S} F \cdot ds = \int_{\partial S} \omega$$

So

$$\iint_S d\omega = \int_{\partial S} \omega.$$

Divergence Theorem:

Let $W \subseteq \mathbb{R}^3$ be an elementary region with ∂W , a closed surface given the outward orientation. Let F be a smooth vector field on W , then:

$$\iiint_W (\operatorname{div}(F)) dV = \iint_{\partial W} F \cdot dS.$$

To show this is just Stokes' Theorem with $M = W$, we need to show that if $\omega = F \cdot dS$, then $d\omega = \operatorname{div}(F) dV$.

We just saw in our discussion of Stokes' Theorem for surfaces that:

$$dS = (dy \wedge dz)\vec{i} + (dz \wedge dx)\vec{j} + (dx \wedge dy)\vec{k}.$$

If $F(x, y, z) = F_1\vec{i} + F_2\vec{j} + F_3\vec{k}$, then:

$$\omega = F \cdot dS = F_1 dy \wedge dz + F_2 dz \wedge dx + F_3 dx \wedge dy.$$

We need to show $d\omega = (\operatorname{div}(F))dx \, dy \, dz$.

$$\begin{aligned} d\omega &= \frac{\partial F_1}{\partial x} dx \wedge dy \wedge dz + \frac{\partial F_2}{\partial y} dy \wedge dz \wedge dx + \frac{\partial F_3}{\partial z} dz \wedge dx \wedge dy \\ &= \left(\frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} \right) dx \wedge dy \wedge dz. \end{aligned}$$

So if $\omega = F \cdot dS$, then $d\omega = \operatorname{div}(F)dx \, dy \, dz$. Thus, the Divergence Theorem says:

$$\iiint_W (\operatorname{div}(F))dV = \iint_{\partial W} F \cdot dS$$

Or

$$\iiint_W d\omega = \iint_{\partial W} \omega.$$